# Multivariate Saddle integrals, 5.1, 5.2, and 5.3 based on Analytic Combinatorics in Several Variables by Robin Pemantle and Mark C. Wilson 

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February 20, 2013

## 1 Review of single variable saddle integrals

Recall that Steve showed us:

$$
\int_{\gamma} A(z) e^{-\lambda \phi(z)} d z
$$

is asymptotic to

$$
A\left(z_{0}\right) \sqrt{\frac{2 \pi}{\phi^{\prime \prime}\left(z_{0}\right) \lambda}} e^{-\lambda \phi\left(z_{0}\right)}
$$

and the first few terms in the expansion near the origin as $\lambda \rightarrow \infty$. Remember the proof where the first few coefficients were obtained via analytic inversion, and a mistake was found by Steve regarding the exponent of the big-Oh term.

## 2 Overview of 5.1

We continue with this set up with $A$ as our amplitude and $\phi$ as the phase, both analytic functions, but this time of a vector argument $\mathbf{z}$ along the contour $C$, a $d$-chain in $\mathbb{C}^{d}$. Compared to the one variable case where Theorem 4.1.1 covers all degrees of degeneracy of the phase function $\phi(k \geq 2)$, and all degrees of vanishing of the amplitude function $A$ ( $l \geq 0$ ), for the multivariate case $\phi$ has a much greater range of possibilities.

Recall that in one dimension, we take $k=2$; for higher dimensions, we assume the Hessian matrix

$$
\mathcal{H}:=\left(\frac{\partial^{2} \phi}{\partial z_{j} \partial z_{k}}\right) \neq 0 .
$$

The Taylor series for $\phi$ expanded around the origin is

$$
\phi(\mathbf{z})=\phi(\mathbf{0})+\mathbf{z}^{T} \nabla \phi(\mathbf{0})+\frac{1}{2} \mathbf{z}^{T} \mathcal{H} \mathbf{z}+O\left(|\mathbf{z}|^{3}\right),
$$

hence the Hessian matrix represents twice the quadratic term in the phase, and its nonsingularity is a generalization of non-vanishing of the quadratic term in the univariate case.

Instead of the special phase function $x^{2}$, we will use $S(\mathbf{x})=x_{1}^{2}+\cdots+x_{d}^{2}$ to denote the standard quadratic. Parallel to the development of the univariate case, we will establish the result

$$
A=\text { monomial } \quad \phi=\text { standard quadratic }
$$

coupled with a big-Oh result which allows us to integrate term by term to obtain asymptotics for the standard phase function.

Three main theorems:
Theorem 1 (5.1.1 Standard Phase). Let $A(\mathbf{x})$ be a real analytic function defined on a neighbourhood $\mathcal{N}$ of the origin in $\mathbb{R}^{d}$ with a series expansion

$$
A(\mathbf{x}):=\sum_{r_{1}, \ldots, r_{d}} x_{1}^{r_{1}} \cdots x_{d}^{r_{d}}=\sum_{\mathbf{r}} a_{\mathbf{r}} \mathbf{x}^{\mathbf{r}}
$$

Let

$$
I(\lambda):=\int_{\mathcal{N}} A(\mathbf{x}) e^{-\lambda S(\mathbf{x})} d \mathbf{x}
$$

Then an asymptotic series expansion for $I(\lambda)$ in increasing $|\mathbf{r}|$ is

$$
I(\lambda) \sim \sum_{n} \sum_{|\mathbf{r}|=n} a_{\mathbf{r}} \beta_{\mathbf{r}} \lambda^{-(|r|+d) / 2}
$$

where $\beta_{\mathbf{r}}=0$ if any $r_{j}$ is odd, and

$$
\beta_{2 m}=\sqrt{\pi}^{d} \cdot \prod_{j=1}^{d} \frac{\left(2 m_{j}\right)!}{m_{j}!4^{m_{j}}}
$$

otherwise.
Theorem 2 (5.1.2 $\operatorname{Re}(\phi)$ has a strict minimum). Suppose that the real part of $\phi$ is strictly positive except at the origin and that its Hessian matrix $\mathcal{H}$ is non-singular there. Let $A$ be any analytic function not vanishing at the origin and define

$$
I(\lambda):=\int_{\mathcal{N}} A(z) e^{-\lambda \phi(z)} d z
$$

Then

$$
I(\lambda) \sim \sum_{l \geq 0} c_{l} \lambda^{-d / 2-l}
$$

where

$$
c_{0}=A(0) \cdot \frac{\sqrt{2 \pi}^{-d}}{\sqrt{\operatorname{det}(\mathcal{H})}}
$$

and the choice of sign is defined by taking the product of the principal square roots of the eigenvalues of $\mathcal{H}$.

Theorem 3 (5.4.8 Critical point decomposition for stratified spaces). Let $A$ and $\phi$ be analytic functions on a neighbourhood of a stratified space $\mathcal{M} \subseteq \mathbb{C}^{d}$. If $\phi$ has finitely many critical points on $\mathcal{M}$, then

$$
I(\lambda) \sim(2 \pi \lambda)^{-d / 2} \sum_{\mathbf{x}} A(\mathbf{x}) e^{\lambda \phi(\mathbf{x})} \operatorname{det}(\mathcal{H}(\mathbf{x}))^{-1 / 2}
$$

where

$$
\mathcal{H}(\mathbf{x}) \text { is the Hessian for } \phi \text { at } \mathbf{x} \text {, }
$$

and the sum is over the critical points $\mathbf{x}$ at which the real part of $\phi$ is minimized.

## 3 5.2 Standard phase

Remember how Steve developed the single variate case by starting at the simplest case:

$$
A=\text { monomial } \quad \text { and } \quad \phi=x^{2} .
$$

We will begin with a proposition which evaluates a real integral exactly.
Proposition 4 (5.2.1). The integral

$$
\int_{-\infty}^{\infty} x^{2 n} e^{-x^{2}} d x=\beta_{2 n}=\sqrt{\pi} \cdot \frac{(2 n)!}{n!4^{n}}
$$

Note that the exponent of the monomial $A$ is $2 n$, and the exponent of the monomial and monic $\phi$ is 2 .

Proof. We will prove this proposition by induction.
The basis step is when $n=0$. This is, up to a change of variables and observation of symmetry, the standard Gaussian integral and is in fact the definition of $\Gamma(1 / 2)$ - which is $\sqrt{\pi}$. This can be checked directly using the substitution $u=x^{2}$ in the integral.

The inductive step is to assume the result for $n-1$. We use integration by parts to get

$$
\begin{aligned}
\int_{-\infty}^{\infty} x^{2 n} e^{-x^{2}} d x & =\int_{-\infty}^{\infty} \frac{x^{2 n-1}}{-2}\left(-2 x e^{-x^{2}}\right) d x \\
& =\left.\frac{-x^{2 n-1}}{2} \cdot e^{-x^{2}}\right|_{-\infty} ^{\infty}-\int_{-\infty}^{\infty} \frac{(2 n-1) x^{2 n-2}}{-2} e^{-x^{2}} d x \\
& =0+\frac{2 n-1}{2} \sqrt{\pi} \cdot \frac{(2 n-2)!}{(n-1)!4^{n-1}}
\end{aligned}
$$

by the inductive hypothesis, and the result follows from multiplying and dividing the expression by $2 n$.

Since the result for $n-1$ implies the result for $n$, by mathematical induction we have shown that the result of the proposition holds.

Now we can vary the phase function $\phi$ so that it is no longer monic, but has a factor of $\lambda$. This is stated in the next Corollary.

Corollary 5 (5.2.2).

$$
\int_{-\infty}^{\infty} x^{2 n} e^{-\lambda x^{2}} d x=\beta_{2 n} \lambda^{-1 / 2-n}
$$

Proof. We just need a change of variables $y=\sqrt{\lambda} x$. This implies $d y=\sqrt{\lambda} d x$ and thus

$$
\int_{-\infty}^{\infty} x^{2 n} e^{-\lambda x^{2}} d x=\int_{-\infty}^{\infty} \frac{1}{\lambda^{n} \cdot \sqrt{\lambda}} y^{2 n} e^{-y^{2}} d x=\lambda^{-n-1 / 2} \beta_{2 n}
$$

Corollary 6 (5.2.3 Higher dimensional monomial integral). Let $\mathbf{r}$ be a d-vector of nonnegative integers. Then

$$
\int_{-\infty}^{\infty} \int_{-\infty}^{\infty} \ldots \int_{-\infty}^{\infty} x_{1}^{r_{1}} x_{2}^{r_{2}} \ldots x_{d}^{r_{d}} e^{-\lambda\left(x_{1}^{2}+x_{2}^{2}+\ldots+x_{d}^{2}\right)} d x_{1} d x_{2} \ldots d x_{d}=\prod_{j=1}^{d} \beta_{r_{j}} \cdot \lambda^{-(d+\mid \mathbf{r}) / 2}
$$

where $\beta_{r_{j}}=0$ if $r_{j}$ is odd (and thus the integral is nonzero only when each $r_{j}$ is even).
Proof. When our integral is written out as a $d$-dimensional integral, you can see how integrating each dimension separately implies the integral has the value

$$
\begin{aligned}
\prod_{j=1}^{d}\left(\int_{-\infty}^{\infty} x_{j}^{r_{j}} e^{-\lambda x_{j}^{2}} d x_{j}\right) & =\prod_{j=1}^{d} \beta_{r_{j}} \lambda^{-\left(1+r_{j}\right) / 2} \\
& =\prod_{j=1}^{d} \beta_{r_{j}} \cdot \lambda^{-(d+|\mathbf{r}|) / 2}
\end{aligned}
$$

Proposition 7 (5.2.4 big-O estimate). Let $A$ be any smooth function satisfying a big- $O$ bound at the origin

$$
A(\mathbf{x})=O\left(|\mathbf{x}|^{r}\right)
$$

where the norm is the Euclidean norm, and $r$ is just some positive real number, not a vector as in previous corollary. Then the integral over any connected compact set $K$ containing the origin may be bounded from above by

$$
\int_{K} A(\mathbf{x}) e^{-\lambda S(\mathbf{x})} d x=O\left(\lambda^{-(d+r) / 2}\right)
$$

The implied constant on the right goes to zero as the constant in the hypothesis of the upper bound goes to zero.

Proof. 1. Because $K$ contains the origin, is connected, compact, and $A(\mathbf{x})=O\left(|\mathbf{x}|^{r}\right)$ at the origin, there exists a constant $c$ such that $|A(\mathbf{x})| \leq c|\mathbf{x}|^{r}$ in $K$.
2. Let us create a sequence of sets that are intersections of $K$ with either the ball

$$
K_{0}:=\left\{\mathbf{x}:|\mathbf{x}| \leq \lambda^{-1 / 2}\right\}
$$

or the shells

$$
K_{n}:=K \cap\left\{2^{n-1} \lambda^{-1 / 2} \leq|\mathbf{x}| \leq 2^{n} \lambda^{-1 / 2}\right\} .
$$

These sets help us say more precisely how $|A(\mathbf{x})|$ is bounded.
3. We can also bound

$$
\int_{K_{0}} e^{-\lambda S(\mathbf{x})} d \mathbf{x} \leq \int_{K_{0}} d \mathbf{x} \leq c_{d} \lambda^{-d / 2}
$$

for some constant $c_{d}$. Thus, combining the previous points gives

$$
\left|\int_{K_{0}} A(\mathbf{x}) e^{-\lambda S(\mathbf{x})} d \mathbf{x}\right| \leq c^{\prime} \lambda^{-(r+d) / 2}
$$

4. For $n \geq 1$, on $K_{n}$ we use $A$ 's big-O bound to obtain

$$
|A(\mathbf{x})|=O\left(|\mathbf{x}|^{r}\right) \leq 2^{r n} \cdot c \cdot \lambda^{-r / 2}
$$

5. We can use our bound on $|\mathbf{x}|$ between the shells to give us a bound on $|\mathbf{x}|^{2}$

$$
2^{2 n-2} / \lambda \leq|\mathbf{x}|^{2} \leq 2^{n} / \lambda
$$

Thus,

$$
e^{-\lambda S(\mathbf{x})} \leq e^{-2^{2 n-2}}
$$

6. Finally, the integral bound in $K_{n}$ is

$$
\int_{K_{n}} d \mathbf{x} \leq 2^{d n} c_{d} \lambda^{-d / 2}
$$

7. Combining the last three bounds, we have the bound for the entire integral by summing over all the shells. Let

$$
c^{\prime \prime}=c \cdot c_{d} \sum_{n=1}^{\infty} 2^{(d+r) n} e^{-2^{2 n-2}}<\infty
$$

Then

$$
\int_{K} A(\mathbf{x}) e^{-\lambda S(\mathbf{x})} d \mathbf{x}=\sum_{k=0}^{\infty}\left|\int_{K_{n}} A(\mathbf{x}) e^{-\lambda S(\mathbf{x})} d \mathbf{x}\right| \leq\left(c^{\prime}+c^{\prime \prime}\right) \lambda^{-(r+d) / 2}
$$

These four propositions and corollaries make it easier to construct the proof of Theorem 5.1.1. (Standard Phase).

Proof of Theorem 5.1.1. Write $A(\mathbf{x})$ as a power series up to degree $N$ plus a remainder term:

$$
A(\mathbf{x})=\sum_{n=0}^{N}\left(\sum_{|\mathbf{r}|=n} a_{\mathbf{r}} x^{\mathbf{r}}\right)+R(\mathbf{x})
$$

where $R(\mathbf{x})=O\left(|\mathbf{x}|^{N+1}\right)$.
Now we have a monomial part of $A$, along with a big-O estimate. Using Corollary 5.2.3 on the monomial integral and Proposition 5.2 .4 on the big-O estimate thus implies the desired result:

$$
I(\lambda)=\sum_{n=0}^{N}\left(\sum_{|\mathbf{r}|=n} a_{\mathbf{r}} \beta_{\mathbf{r}} \lambda^{-(n+d) / 2}\right)+O\left(\lambda^{-(N+1+d) / 2}\right)
$$

## 4 5.3 Real part of phase has a strict minimum

Here, we have the set up:

1. Let $\mathcal{N}$ be a neighbourhood of the origin in $\mathbb{R}^{d}$.
2. We have an analytic $\phi: \mathcal{N} \rightarrow \mathbb{C}^{d}$ which is represented by a power series that converges on $\mathcal{N}$.
3. Such a $\phi$ may be extended to a holomorphic function on a neighbourhood $\mathcal{N}_{\mathbb{C}}$ of the origin in complex $d$-dim space.
4. Now, suppose $\phi(\mathbf{0})=0$ and the real part of $\phi$ is non-negative on $\mathcal{N}$. This section's assumption that the real part of phase $\phi$ has a strict minimum implies that the gradient of $\phi$ must vanish at the origin.
5. We say that $\phi$ has a quadratically non-degenerate critical point at the origin if the quadratic part of $\phi$ is non-degenerate.
6. Recall in the expansion of $\phi$ where the quadratic part of $\phi$ is a quadratic form represented by

$$
\frac{1}{2} z^{T} \mathcal{H} z
$$

7. Non-degeneracy of a quadratic form means non-singularity of the Hessian $\mathcal{H}$; the determinant of a quadratic form means the determinant of $\mathcal{H}$.
8. Review of Hessian behaviour under a change of variables: If $\psi: \mathbb{C}^{d} \rightarrow \mathbb{C}^{d}$ is a biholomorphic map, $\nabla \phi(\psi(\mathbf{y}))=0$ when $\psi(y)=x$, and the Hessian matrix $\mathcal{H}$ exists there, then the Hessian matrix $\mathcal{H}^{\prime}$ of the composed map $\phi \circ \psi$ at $\mathbf{y}$ is given by

$$
\mathcal{H}^{\prime}=J_{\psi}^{T} \mathcal{H} J_{\psi}
$$

where $J_{\psi}$ is the Jacobian matrix of the map $\psi$ at $\mathbf{y}$ :

$$
J_{\psi}=\left(\begin{array}{ccc}
\frac{\partial \psi_{1}}{\partial y_{1}} & \cdots & \frac{\partial \psi_{1}}{\partial y_{d}} \\
\vdots & \ddots & \vdots \\
\frac{\partial \psi_{d}}{\partial y_{1}} & \cdots & \frac{\partial \psi_{d}}{\partial y_{d}}
\end{array}\right) .
$$

We need two lemmas before the proof of Theorem 5.1.2 ( $\operatorname{Re}(\phi)$ has a strict minimum). The first lemma reassures us that near the origin, if $\psi$ is not of our standard quadratic form $S(\mathbf{x})$ then we can find local coordinates to change $\mathbf{x}$ into $\mathbf{y}$ where a standard quadratic form is attained. The second lemma provides the equivalence between verifying the sign choice of a composed derivative in the multivariate case and a determinantal condition.

Lemma 8 (5.3.1). There is a bi-holomorphic change of variables $\mathbf{x}=\psi(\mathbf{y})$ such that

$$
\phi(\psi(\mathbf{y}))=S(\mathbf{y})=y_{1}^{2}+\cdots+y_{d}^{2} .
$$

The differential

$$
J_{\psi}=d \psi(0) \quad \text { satisfies } \quad\left(\operatorname{det} J_{\psi}\right)^{2}=\frac{1}{\operatorname{det}(\mathcal{H}(\phi) / 2)}
$$

Recall what Nicolas taught us about Morse theory - this lemma is the Morse Lemma.
Proof. Let us do the easy part first: consider

$$
\tilde{\mathcal{H}}(S)=J_{\psi}^{T} \mathcal{H}(\phi) J_{\psi} .
$$

Compute the Hessian of the standard quadratic form $S$ to get $\tilde{\mathcal{H}}(S)=2 I$, where $I$ is the identity matrix. Then

$$
1=\operatorname{det}(\tilde{\mathcal{H}}(S) / 2)=\operatorname{det}\left(J_{\psi}^{T} \frac{\mathcal{H}(\phi)}{2} J_{\psi}\right)=\operatorname{det}\left(J_{\psi}\right)^{2} \cdot \operatorname{det}(\mathcal{H}(\phi) / 2),
$$

and thus

$$
\left(\operatorname{det} J_{\psi}\right)^{2}=\frac{1}{\operatorname{det}(\mathcal{H}(\phi) / 2)} .
$$

The long part is the change of variables where we break the part into three steps.
Step 1 Rewrite $\phi(\mathbf{x})$ as an expansion in coordinates $x_{j} x_{k}$ multiplied by the entries of $\mathcal{H}$.

Step 2 Use mathematical induction to morph the $y_{j}$ 's one at a time into the standard quadratic form by assuming that none of the diagonal entries of the Hessian is 0 .

Step 3 Take care of the case when some diagonal entry of the Hessian is 0 by using a unitary conjugation.

Lemma 9 (5.3.2). Let $W \subseteq \mathbb{C}^{d}$ be the set $\{\mathbf{z}: \operatorname{Re}(S(\mathbf{z}))>0\}$. Pick any $\alpha \in \mathrm{GL}_{d}(\mathbb{C})$ mapping $\mathbb{R}^{d}$ into $\bar{W}$, and let $M:=\alpha^{\dagger} \alpha$ be the matrix representing $S \circ \alpha$. Let $\pi: \mathbb{C}^{d} \rightarrow \mathbb{R}^{d}$ be the projection onto the real part. Then $\pi \circ \alpha$ is orientation preserving on $\mathbb{R}^{d}$ iff $\operatorname{det} \alpha$ is the product of the principal square roots of the eigenvalues of $M$.

Proof. We will need lots of linear algebra in this proof.
First suppose $\alpha \in \mathrm{GL}_{d}(\mathbb{R})$. Then $M:=\alpha^{T} \alpha$ is Hermition and thus has an eigendecomposition $M=P^{-1} D P$. As $z M z^{T}=\left(z \alpha^{T}\right)\left(z \alpha^{T}\right)^{T}=\left|z \alpha^{T}\right|^{2} \geq 0$ for all $z$, we see that $y D y^{T} \geq 0$ by a change of variables. As $D$ is a diagonal matix whose entries are the eigenvalues of $M$, these eigenvalues are positive. Therefore, the product of their principal square roots is positive.

The map $\pi$ is the identity on $\mathbb{R}^{d}$, so an equivalent statement would be: The linear transformation $\alpha$ preserves orientation iff it has positive determinant. (This is true by definition).

In general, define $\alpha_{t}:=\pi_{t} \circ \alpha$, where

$$
\pi_{t}(\mathbf{z})=\Re\{\mathbf{z}\}+(1-t) i \Im\{\mathbf{z}\} .
$$

This should remind us of the homotopic map Nicolas showed us last semester.
For all $0 \leq t \leq 1$,

$$
\pi_{t}\left(\mathbb{R}^{d}\right) \subseteq \bar{W}
$$

so $M_{t}:=\alpha_{t}^{T} \alpha_{t}$ has eigenvalues with nonnegative real parts.
The product of the principal square roots of the eigenvalues is a continuous function on the set of non-singular matrices with no negative real eigenvalues. The determinant of $\alpha_{t}$ is a continuous function of $t$, and when $t=1$ we have seen that it agrees with the product of principal square roots of eigenvalues of $M_{t}$; thus by continuity, this is the correct sign choice for all $0 \leq t \leq 1$. We take $t=0$ to prove the lemma.

Proof of Theorem 5.1.2: Re( $\phi$ ) has a strict minimum. The power series we got from Theorem 5.1.1 allows us to extend $\phi$ to a neighbourhood of the origin in $\mathbb{C}^{d}$.

Using Lemma 5.3.1, we can apply the change of variables $\psi$ to turn a random $\phi$ into a standard quadratic:

$$
I(\lambda)=\int_{\psi^{-1} \mathcal{C}} A \circ \psi(\mathbf{y}) e^{-\lambda S(\mathbf{y})} \operatorname{det}(d \psi(\mathbf{y})) d \mathbf{y}=\int_{\psi^{-1} \mathcal{C}} \tilde{A}(\mathbf{y}) e^{-\lambda S(\mathbf{y})} d \mathbf{y}
$$

where $\mathcal{C}$ is a neighbourhood of the origin in $\mathbb{R}^{d}$ with the standard orientation.

Here, we need to check that we can move the chain $\psi^{-1} \mathcal{C}$ of integration back to the real plane. If successful, then Theorem 5.1.1 can be used to yield the desired expansion in powers $\lambda^{-(d / 2+l)}$.

Take the real part of $S(\mathbf{z})$ and call it $h(\mathbf{z})$. The chain $\mathcal{C}^{\prime}:=\psi^{-1}(\mathcal{C})$ lies in the region $\left\{\mathbf{z} \in \mathbb{C}^{d}: h(\mathbf{z})>0\right\}$ except when $\mathbf{z}=\mathbf{0}$, and in particular $h \geq \epsilon>0$ on $\partial \mathcal{C}^{\prime}$.

Next, we will define a homotopy from the identity map to the map $\pi$ projecting out the imaginary part of $\mathbf{z}$. For any chain $\sigma$ where the integration takes place, this homotopy induces a chain homotopy supported on the image of the support of $\sigma$ under the homotopy. Let

$$
H(\mathbf{z}, t):=\Re\{\mathbf{z}\}+(1-t) i \Im\{\mathbf{z}\} .
$$

Then $H(\sigma)$ is a chain homotopy satisfying

$$
\partial H(\sigma)=\sigma-\pi \sigma+H(\partial \sigma)
$$

With $\sigma=C^{\prime}$, in addition to observing that $S(H(\mathbf{z}, t)) \geq S(\mathbf{z})$, we see there is a $d+1$-chain $\mathcal{D}$ with

$$
\partial \mathcal{D}=C^{\prime}-\pi C^{\prime}+C^{\prime \prime}
$$

and $\mathcal{C}^{\prime \prime}$ supported on $\{h>\epsilon\}$.
Recall Stokes' Theorem: $\int \partial_{D} w=\int_{D} d w=0$ when $w$ is a holomorphic $d$-form. Here we use $\partial_{D}=C^{\prime}-\pi C^{\prime}+C^{\prime \prime}$ to obtain

$$
\int_{C^{\prime}} w=\int_{\pi C^{\prime}} w-\int_{C^{\prime \prime}} w .
$$

Taking $w=\tilde{A} e^{-\lambda S}$ and noting $\int_{C^{\prime \prime}} w=O\left(e^{-\lambda \epsilon}\right)$, this tells us

$$
I(\lambda)=\int_{\pi C^{\prime}} \tilde{A}(\mathbf{y}) e^{-\lambda S(\mathbf{y})} d \mathbf{y}+O\left(e^{-\lambda \epsilon}\right)
$$

The integral in the above expression is looked after by the last lemma.

